

Sparse Paged Grid and its Applications to Adaptivity and Material Point Method

Ming Gao

Motivation - expanding feature set

Wet cloth - [Fei et al. 18]

Snow - [Stomakhin et al. 13]

Viscous fluid - [Larionov et al. 17]

Melting - [Stomakhin et al. 14]

Motivation - accelerating performance

OpenVDB - [Museth et al. 13]

Cloth - [Tang et al. 16]

PhysGrid - [Milne et al. 16]

Fluid - [Wu et al. 18]

Feature breadth vs. optimal performance

Sparse paged grid

Material point method

Adaptivity

SCA 14

Our Method

Ex-rotated Skinning

Eurographics 16

SIGGRAPH 17

SIGGRAPH 18

SIGGRAPH Asia 17

SIGGRAPH Asia 18 (under review)

SPGrid / Adaptivity

SPGrid / MPM

SPGrid / MPM / Adaptivity

SPGrid / MPM / GPU

Sparse paged grid (SPGrid)

Setaluri et al. 14

Sparsity

Liu et al. 16

Resolution: $8192 \times 8192 \times 4096$

Sparsity

128 TB

Virtual memory

Cell ordering

Cell ordering

4 KB

4 KB

Stencil operations

Memory

Dense array

Octree

Stencil operations

SPGrid

Material point method (MPM)

Stomakhin et al. 13

y

Gao et al. 18

Discretization schemes

Discretization schemes

Grid

Particle

Discretization schemes

Grid

Particle

Hybrid

Particle communication

SPH

MPM

Particle communication

SPH

MPM

Particle communication

SPH

MPM

Sparsity

Gao et al. 18

Gao et al. 17

Power Diagrams and Sparse Paged Grids for High Resolution Adaptive Liquids

Power Diagrams and Sparse Paged Grids for High Resolution Adaptive Liquids

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Fig. 1. (Left) Water filling a river bed surrounded by a canyon, with effective resolution $512^2 \times 1024$. Three refinement levels are used, based on proximity to the terrain. (Right) Sources inject water into a container and collide to form a thin sheet, with effective resolution 512^3 . Adaptivity pattern shown on background.

We present an efficient and scalable octree-inspired fluid simulation framework with the flexibility to leverage adaptivity in any part of the computational domain, even when resolution transitions reach the free surface. Our methodology ensures symmetry, definiteness and second order accuracy of the discrete Poisson operator, and eliminates numerical and visual artifacts of prior octree schemes. This is achieved by adapting the operators acting on the octree's simulation variables to reflect the structure and connectivity of a *power diagram*, which recovers primal-dual mesh orthogonality and eliminates problematic T-junction configurations. We show how such operators can be efficiently implemented using a pyramid of sparsely populated uniform grids, enhancing the regularity of operations and facilitating parallelization. A novel scheme is proposed for encoding the topology of the power diagram in the neighborhood of each octree cell, allowing us to locally reconstruct it on the fly via a lookup table, rather than resorting to costly explicit meshing. The pressure Poisson equation is solved via a highly efficient, matrix-free multigrid preconditioner for Conjugate Gradient, adapted to the power diagram discretization. We use another sparsely

* M. Aanjaneya was with the University of Wisconsin - Madison during this work. This work was supported in part by National Science Foundation grants IIS-1253598, CCF-1423064, CCF-1533885 and by the Natural Sciences and Engineering Research Council of Canada under grant RGPIN-04360-2014. The authors are grateful to Nathan Mitchell for his indispensable help with modeling and rendering of examples. C. Batty would like to thank Ted Ying for carrying out preliminary explorations on quadtrees. Permission to make digital or hard copies of all or part of this work for personal or classroom use is granted without fee provided that copies are not made or distributed for profit or commercial advantage and that copies bear this notice and the full citation on the first page. Copyrights for components of this work owned by others than ACM must be honored. Abstracting with credit is permitted. To copy otherwise, or republish, to post on servers or to redistribute to lists, requires prior specific permission and/or a fee. Request permissions from permissions@acm.org.

© 2017 ACM. 0730-0301/2017/7-ART140 \$15.00 DOI: http://dx.doi.org/10.1145/3072959.3073625

populated uniform grid for high resolution interface tracking with a narrow band level set representation. Using the recently introduced SPGrid data structure, sparse uniform grids in both the power diagram discretization and our narrow band level set can be compactly stored and efficiently updated via streaming operations. Additionally, we present enhancements to adaptive level set advection, velocity extrapolation, and the fast marching method for redistancing. Our overall framework gracefully accommodates the task of dynamically adapting the octree topology during simulation. We demonstrate end-to-end simulations of complex adaptive flows in irregularly shaped domains, with tens of millions of degrees of freedom.

 $\texttt{CCS Concepts:} \bullet \textbf{Computing methodologies} \to \textbf{Physical simulation};$

Additional Key Words and Phrases: Power diagrams, Octrees, Adaptivity ACM Reference format:

Mridul Aanjaneya, Ming Gao, Haixiang Liu, Christopher Batty, and Eftychios Sifakis. 2017. Power Diagrams and Sparse Paged Grids for High Resolution Adaptive Liquids. *ACM Trans. Graph.* 36, 4, Article 140 (July 2017), 12 pages. DOI: http://dx.doi.org/10.1145/3072959.3073625

1 INTRODUCTION

Liquids exhibit complex and detailed motion across a vast range of scales, from tiny ripples to huge waves; this fact motivates the desire for liquid simulation tools that can handle ever increasing levels of resolution. While a key avenue towards this goal is the development of more efficient numerical methods on regular uniform grids that conserve mass with large time steps [Chentanez and Müller 2012; Lentine et al. 2011, 2012] and allow for fast pressure projection [Ando et al. 2015; Dick et al. 2016; Lentine et al. 2010; Liu

ACM Transactions on Graphics, Vol. 36, No. 4, Article 140. Publication date: July 2017.

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- ACM Transactions on Graphics (Proceedings of
- ACM SIGGRAPH), 2017

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Previous work

Setaluri et al. 14

Previous work

Setaluri et al. 14

Losasso et al. 04

Previous work

Setaluri et al. 14

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Loss of orthogonality

Barrier

Fluid region 1 Fluid region 2

Pressure

Force

Loss of orthogonality

Pressure Force Velocity component

Staggered grid

Loss of orthogonality

Spurious motions

Unstructured mesh

Ando et al. 13

Our solution: power diagram

Comparison

Opportunities

• Power diagram ensures orthogonality

• Can still use octree for storage

Accelerate via SPGrid

Further technicalities (see thesis)

• Minor topological complications (3D)

Velocity interpolation

• Retrieval of Poisson equation stencils

Results



Results



An Adaptive Generalized Interpolation Material Point Method for Simulating Elastoplastic Materials

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Fig. 1. Left: An elastoplastic model is dropped into a plane with a thin perforation pattern; our adaptive discretization allows the material to drip through Right: Adaptive sand simulation with a visualization of the underlying grid refinement. We color refined particles with blue and coarse ones with green.

We present an adaptive Generalized Interpolation Material Point (GIMP) method for simulating elastoplastic materials. Our approach allows adaptive refining and coarsening of different regions of the material, leading to an efficient MPM solver that concentrates most of the computation resources in specific regions of interest. We propose a C^1 continuous adaptive basis function that satisfies the partition of unity property and remains nonnegative throughout the computational domain. We develop a practical strategy for particle-grid transfers that leverages the recently introduced SPGrid data structure for storing sparse multi-layered grids. We demonstrate the robustness and efficiency of our method on the simulation of various elastic and plastic materials. We also compare key kernel components to uniform grid MPM solvers to highlight performance benefits of our method.

 $\label{eq:CCS} \text{Concepts:} \bullet \textbf{Computing methodologies} \to \textbf{Physical simulation};$

Additional Key Words and Phrases: Material Point Method (MPM), Generalized Interpolation Material Point (GIMP), Adaptive grids, Elastoplasticity

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ACM Reference format:

Ming Gao, Andre Pradhana Tampubolon, Chenfanfu Jiang, and Eftychios Sifakis. 2017. An Adaptive Generalized Interpolation Material Point Method for Simulating Elastoplastic Materials. ACM Trans. Graph. 36, 6, Article 223 (November 2017), 12 pages. DOI: 10.1145/3130800.3130879

1 INTRODUCTION

The Material Point Method (MPM) has been attracting considerable interest since it was introduced to the field of computer graphics by Stomakhin et al. [2013]. Combining advantages from both Lagrangian particle representation and Eulerian grid representation, MPM proves to be especially effective for animating elastoplastic materials undergoing large deformation or topology change [Jiang et al. 2016]. Despite its physical realism and geometrical convenience, a traditional MPM solver has several disadvantages. First, it is more computationally expensive than mesh-based Lagrangian approaches such as those based on Finite Element Methods (FEM) [Sifakis and Barbic 2012]. The bottleneck of MPM is usually the costly transfer operations between the particles and the grid. The cost of such transfer operations is particularly evident when we realize that MPM has to maintain the same grid resolution and a sufficient particle count hout the simulation domain. The overhead of this process is highlighted in scenarios such as the example of drawing in a

ACM Transactions on Graphics, Vol. 36, No. 6, Article 223. Publication date: November 2017.

An Adaptive Generalized Interpolation Material Point Method for Simulating Elastoplastic Materials

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- ACM Transactions on Graphics (Proceedings of
- ACM SIGGRAPH Asia), 2017



Motivation



Motivation







Motivation









MPM adaptivity





















C¹ continuity

Weight / mass



Weight gradient / force

Steffen et al. 08

C⁰ continuity

Weight / mass



Steffen et al. 08

Weight gradient / force



C¹ continuity in octree ?

Weight / mass





Weight gradient / force

Steffen et al. 08

C⁰ from uniform to quadtree





Uniform



Quadtree

Embedding T-junctions

DOF node

Embedded node / T-junction node



Free node



Step1 - set all nodes free





• Free node



Free nodeT-junction node



- Free node
- T-junction node
- Parent node



- Free node
- T-junction node
- Parent node





- Free node
- T-junction node
- Parent node





- Free node
- T-junction node
- Parent node



Step 3 - upgrade to C¹ continuity -2 -1





Step 3 - upgrade to C¹ continuity

• Free node







Parallelism optimization



- Free node
- Ghost node
- T-junction node



Parallelism optimization



	Tan 02	Ma 05
C1 continuity	No	Yes
Partition of unity	Yes	Yes
Non- negativity	Yes	Yes
Arbitrary octree	Yes	No
Ease of parallelism	Hard	Maybe

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Y.P. Lian, P.F. Yang, X. Zhang, F. Zhang, Y. Liu, and P. Huang. 2015. A mesh-grading material point method and its parallelization for problems with localized extreme deformation. Comp Meth App Mech Eng 289 (2015), 291 – 315.



Results



Results



Animating Fluid Sediment Mixture in Particle-Laden Flows

Animating Fluid Sediment Mixture in Particle-Laden Flows

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Fig. 1. Sediment transport: Our method can animate intricate two-way coupled particle-laden flows such as sediment transport in liquid.

In this paper, we present a mixed explicit and semi-implicit Material Point Method for simulating particle-laden flows. We develop a Multigrid Preconditioned fluid solver for the Locally Averaged Navier Stokes equation. This is discretized purely on a semi-staggered standard MPM grid. Sedimentation is modeled with the Drucker-Prager elastoplasticity flow rule, enhanced by a novel particle density estimation method for converting particles between representations of either continuum or discrete points. Fluid and sediment are two-way coupled through a momentum exchange force that can be easily resolved with two MPM background grids. We present various results to demonstrate the efficacy of our method.

CCS Concepts: • **Computing methodologies** → **Physical simulation**;

Additional Key Words and Phrases: Material Point Method (MPM), particlefluid interaction, multiphase, sedimentation, sediment transport

ACM Reference format:

Ming Gao, Andre Pradhana, Xuchen Han, Qi Guo, Grant Kot, Eftychios Sifakis, and Chenfanfu Jiang. 2018. Animating Fluid Sediment Mixture in Particle-Laden Flows. *ACM Trans. Graph.* 37, 4, Article 1 (August 2018), 11 pages.

DOI: 10.1145/3197517.3201309

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© 2018 ACM. 0750-0501/2018/8-AR11 \$15. DOI: 10.1145/3197517.3201309

1 INTRODUCTION

Recently, multi-phase multi-material simulations are increasingly gaining attention from computer graphics researchers. Simulating various phases or materials in a unified framework is particularly favored. Existing work includes coupled Lagrangian particle simulation with Position Based Dynamics (PBD) [Macklin et al. 2014], water-gas mixtures [Nielsen and Østerby 2013] with an Eulerian method, solid-fluid phase-change [Stomakhin et al. 2014] and porous granular media [Pradhana-Tampubolon et al. 2017] with Material Point Method (MPM), as well as interactive solids and fluids based on the mixture model with Smoothed Particle Hydrodynamics (SPH) [Yan et al. 2016].

Most of the existing approaches are based on *continuum* mixture theory [Manninen et al. 1996]. The continuum assumption for each material phase is essential for simulations of macroscopic porous media (e.g., landslides and liquid blending). However, it may fail to capture the correct behavior of particle-laden flows where the solid phase is on a relatively small scale. Note that particle-laden sediment flow is ubiquitous in natural systems. Typical examples include sediment transport, sedimentation, volcano eruption, dune migration by erosion with ripples, and dust storms. The significance of understanding and simulating these phenomena is also recognized in many engineering applications, such as granular material fluidization [van der Hoef et al. 2006] and coastal erosion prediction [Sun and Xiao 2016a].

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- **M. Gao**, A. Tampubolon, X. Han, Q. Guo, G. Kot, E. Sifakis, C. Jiang
- ACM Transactions on Graphics (Proceedings of
- ACM SIGGRAPH), 2018









3 phases 1 point

Approach: mixture in particles vs. grid







2 phases 2 point

Approach: one-way coupling vs. two-way



One way coupling



Two way coupling








Translational interaction

Approach: DEM vs. MPM



Krugger-Emden et al. 05



Approach: DEM vs. MPM



DEM - discrete view

Approach: DEM vs. MPM

DEM - discrete view



MPM - continuum view

Challenge of MPM: handle discrete particles



Volume gain problem



Challenges







Momentum conservation



Results



Results



GPU Optimization of Material Point Method

GPU Optimization of Material Point Methods

Paper ID: 250

ANONYMOUS AUTHOR(S)



Fig. 1. How to melt your dragon. Melting an elastoplastic dragon with 4.2 million particles on a 2563 grid using our GPU-optimized implicit MPM dynamics and heat solvers on a Nvidia Quadro P6000 GPU at an average 10.5 seconds per 48Hz frame.

The Material Point Method (MPM) has been shown to facilitate effective simulations of physically complex and topologically challenging materials, with a wealth of emerging applications in computational engineering and visual computing. Borne out of the extreme importance of regularity, MPM is given attractive parallelization opportunities on high-performance modern multiprocessors. Unlike the conceptually simple CPU parallelization, a GPU optimization of MPM that fully leverages computing resources presents challenges that require exploring an extensive design-space for favorable data structures and algorithms. In this paper we introduce methods for addressing the computational challenges of MPM and extending the capabilities of general simulation systems based on MPM, particularly concentrating on GPU optimization. In addition to our open-source high-performance framework, we also perform performance analyses and benchmark experiments to compare against alternative design choices which may superficially appear to be reasonable, but can suffer from suboptimal performance in practice. Our explicit and fully implicit GPU MPM solvers are further equipped with a Moving Least Squares MPM heat solver and a novel sand constitutive model to enable fast simulations of a wide range of materials. We demonstrate that more than an order of magnitude performance improvement can be achieved with our GPU solvers. Practical high-resolution examples with up to ten million particles run in less than one minute per frame.

CCS Concepts: • Computing methodologies → Physical simulation;

Additional Key Words and Phrases: Material Point Method (MPM), GPU, SPGrid, GVDB, Hybrid Particle/Grid

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ACM Reference format:

Anonymous Author(s). 2018. GPU Optimization of Material Point Methods . ACM Trans. Graph. 1, 1, Article 1 (November 2018), 11 pages. DOI: 10.1145/3197517.3201309

1 INTRODUCTION

The Material Point Method (MPM) is a hybrid Lagrangian/Eulerian computational scheme that has been shown to simulate a large variety of traditionally-challenging materials with visually rich animations in computer graphics. Recent examples of MPM-based methods developed for such materials include simulations of snow [Stomakhin et al. 2013], granular solids [Klár et al. 2016], multi-phase mixtures [Gao et al. 2018; Stomakhin et al. 2014; Tampubolon et al. 2017], cloth [Jiang et al. 2017a] and many others. MPM has been shown to be particularly effective for simulations involving a large number of particles with complex interactions. However, the size and the complexity of these simulations lead to substantial demands on computational resources, thereby limiting the practical use cases of MPM in computer graphics applications.

Using the parallel computation power of today's GPUs is an attractive direction for addressing computational requirements of simulations with MPM. However, the algorithmic composition of an MPM simulation pipeline can pose challenges in fully leveraging compute resources in a GPU implementation. Indeed, MPM simulations include multiple stages with different computational profiles, and the choice of data structures and algorithms used for handling some stages can have cascading effects on the performance of the remaining computation. Thus, discovering how to achieve a performant GPU implementation of MPM involves a software-level sign-space exploration for determining the favorable tions of data structures and algorithms for handling each stage.

M. Gao*, X. Wang*, K. Wu*(joint first authors), A. Tampubolon, E. Sifakis, C. Yuksel, C. Jiang SIGGRAPH Asia 2018 (under review)



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DOI: 10.1145/3197517.3201309

Acceleration for hybrid methods



Klar et al. 17



Wu et al. 18

Target benchmarks



Particles: 9.0 M Grid resolution: 512³ Simulation: 21.88 secs/frame

Particles: 4.2 M Grid resolution: 256[^]3 Simulation: 10.48 secs/frame





GPU - GSPGird CPU - SPGird

Sparsity - (G)SPGrid

CPU virtual memory



GPU memory





Sparsity - GSPGrid







Shared memory

Sparsity - GSPGrid



Shared memory



Shared memory

Sparsity - GSPGrid

Dual block





Block





Write hazards





CUDA thread - •

lane id	0	1	2	3	4	5	6	7
node id	n	n+1	n+1	n+1	n+1	n+2	n+2	n+3

lane id	0	1	2	3	4	5	6	7
node id	n	n+1	n+1	n+1	n+1	n+2	n+2	n+3
attribute mass	m_0	m_1	m_2	m_3	m_4	m_5	m_6	m_7
iteration 0 , stride	1							
mass sum	m_0	$m_1 + m_2$	$m_2 + m_3$	$m_{3} + m_{4}$	m_4	$m_{5} + m_{6}$	m_6	m_7

lane id	0	1	2	3	4	5	6	7
node id	n	n+1	n+1	n+1	n+1	n+2	n+2	n+3
attribute mass	m_0	m_1	m_2	m_3	m_4	m_5	m_6	m_7
iteration 0 , stride 1			- 1 					
mass sum	m_0	$m_1 + m_2$	$m_2 + m_3$	$m_{3} + m_{4}$	m_4	$m_{5} + m_{6}$	m_6	m_7
iteration 1 , stride 2			 - +					
mass sum	m_0	$(m_1+m_2) + (m_3+m_4)$	$(m_2+m_3) + m_4$	$m_{3} + m_{4}$	m_4	$m_{5} + m_{6}$	m_6	m 77

lane id	0	1	2	3	4	5	6	7
node id	n	n+1	n+1	n+1	n+1	n+2	n+2	n+3
attribute mass	m_0	m_1	<i>m</i> ₂	m_3	m_4	m_5	m_6	m_7
iteration 0 , stride	1							
mass sum	m_0	$m_1 + m_2$	$m_2 + m_3$	$m_{3} + m_{4}$	m_4	$m_{5} + m_{6}$	m_6	m_7
iteration 1 , stride	2		- +					
mass sum	m_0	$(m_1+m_2) + (m_3+m_4)$	$(m_2+m_3) + m_4$	$m_{3} + m_{4}$	m_4	$m_{5} + m_{6}$	<i>m</i> ₆	m 7
shared memory	node n	node n+1				node n+2		node n+3

Benchmark



Accelerated particle sorting

Avoiding explicit particle reordering

• A new sand model for semi-implicit integration

A MPM-based heat solver

Additional contributions

Fluid

SPGrid GSPGrid



Conclusion



Jello





Conclusion

Breadth of simulation

Price paid: Platform-s Optimizati Focus on V

Parallel efficiency

Platform-specific solutions Optimizations far from automatic Focus on **visual** appeal

Fluid

SPGrid GSPGrid







Goo

Modeling

Jello

Rendering

3D printing



Acknowledgement

- My advisor: Prof. Eftychios Sifakis
- Committee:
- UW Visual Computing Lab
- External collaborators
- National Science Foundation for funding

• Prof. Michael Gleicher, Dan Negrut, Jean-Luc Thiffeault and Chenfanfu Jiang